# **Perform Rotations**

**Goal** • Rotate figures about a point.

#### **Your Notes**

#### **VOCABULARY**

Center of rotation In a rotation, a figure is turned about a fixed point called the center of rotation.

Angle of rotation In a rotation, rays drawn from the center of rotation to a point and its image form the angle of rotation.

#### Example 1

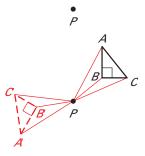
#### Draw a rotation

Draw a 150° rotation of  $\triangle ABC$  about P.

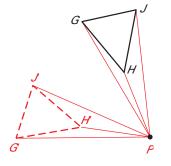
#### **Solution**

- **Step 1 Draw** a segment from A to P.
- Step 2 Draw a ray to form a 150° angle with PA.
- **Step 3 Draw** A' so that PA' = PA.
- **Step 4 Repeat Steps 1–3 for each** vertex. Draw  $\triangle A'B'C'$ .





- **Checkpoint** Complete the following exercise.
  - 1. Draw a 60° rotation of  $\triangle$ GHJ about P.

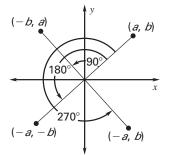


#### **Your Notes**

# COORDINATE RULES FOR ROTATIONS ABOUT THE ORIGIN

When a point (a, b) is rotated counterclockwise about the origin, the following are true:

- **1.** For a rotation of 90°,  $(a, b) \rightarrow (-b, a)$ .
- **2.** For a rotation of 180°,  $(a, b) \rightarrow (-a, -b)$ .
- **3.** For a rotation of 270°,  $(a, b) \rightarrow (b, -a)$ .



### Example 2

#### Rotate a figure using the coordinate rules

Graph quadrilateral *KLMN* with vertices K(3, 2), L(4, 2), M(4, -3), and N(2, -1). Then rotate the quadrilateral 270° about the origin.

#### **Solution**

Graph *KLMN*. Use the coordinate rule for a 270° rotation to find the images of the vertices.

$$(a, b) \rightarrow (b, -a)$$

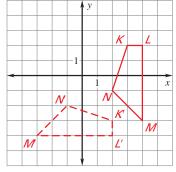
$$K(3,2) \rightarrow K'(2,-3)$$

$$L(4, 2) \rightarrow L'(2, -4)$$

$$M(4, -3) \rightarrow M'(\underline{-3}, \underline{-4})$$

$$N(2, -1) \rightarrow N'(-1, -2)$$

Graph the image K'L'M'N'.



## Checkpoint Complete the following exercise.

2. Graph *KLMN* in Example 2. Then rotate the quadrilateral 90° about the origin.

#### **Your Notes**

Notice that a 360° rotation returns the figure to its original position. The matrix that represents this rotation is called the identity matrix.

**Because matrix** multiplication is

not commutative, always write the

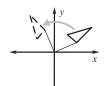
matrix.

rotation matrix first, then the polygon

## **ROTATION MATRICES (COUNTERCLOCKWISE)**

90° rotation

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$



180° rotation

$$\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}$$

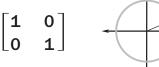


270° rotation

$$\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$



360° rotation



#### Example 3 Use matrices to rotate a figure

Trapezoid DEFG has vertices D(-1, 3), E(1, 3), F(2, 1), and G(1, 0). Find the image matrix for a 180° rotation of DEFG about the origin. Graph DEFG and its image.

#### **Solution**

**Step 1 Write** the polygon matrix:  $\begin{bmatrix} -1 & 1 & 2 & 1 \\ 3 & 3 & 1 & 0 \end{bmatrix}$ 

**Step 2 Multiply** by the matrix for a 180° rotation.

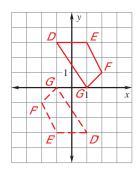
$$\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 2 & 1 \\ 3 & 3 & 1 & 0 \end{bmatrix} = \begin{bmatrix} D' & E' & F' & G' \\ -3 & -1 & -2 & -1 \\ -3 & -3 & 1 & 0 \end{bmatrix}$$

Rotation matrix

**Polygon** matrix

**Image** matrix

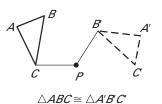
**Step 3 Graph** the preimage *DEFG*. Graph the image D'E'F'G'.



#### **Your Notes**

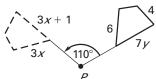
#### **THEOREM 9.3: ROTATION THEOREM**

A rotation is an isometry.



#### **Example 4** Find side lengths in a rotation

The quadrilateral is rotated about P. Find the value of y.



#### **Solution**

By Theorem 9.3, the rotation is an isometry, so corresponding side lengths are equal. Then 3x = 6, so x = 2. Now set up an equation to solve for y.

$$y = 3x + 1$$
 Corresponding lengths in an isometry are equal.

# **Checkpoint** Complete the following exercises.

3. Use the quadrilateral in Example 3. Find the image matrix after a 270° rotation about the origin.

$$\begin{bmatrix}
D & E & F & G' \\
3 & 3 & 1 & 0 \\
1 & -1 & -2 & -1
\end{bmatrix}$$

#### **Homework**

**4.** The triangle is rotated about *P*. Find the value of b.

$$b = 4$$

